

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	7406	((73/162,431,866.1,866.5) or (7/167,168) or (409/204,218,235,264,265,286,337,338,343) or (901/2,10,14,15,16,24,28,41,44,46,47)).CCLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2005/06/30 13:12
L2	7	I1 and ((inspect\$ near (head tool sensor)) with slid\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/30 13:14
L3	2298	I1 and robot\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/30 13:14
L4	1593	I3 and (head tool sensor)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/30 13:15
L5	1593	I4 and ((head tool sensor) with displac\$5)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/30 13:15
L6	216	I4 and ((head tool sensor) with displac\$5)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/30 13:49
L7	31350	(preloaded "pre-loaded" near roller near bearing)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/30 13:49
L8	45	((preloaded "pre-loaded") near roller near bearing)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/30 13:49
S1	8630	parallelogram near link\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 10:40
S2	748	S1 and sensor	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/01/03 07:33
S3	799	S1 and (sensor or probe)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/01/03 08:16
S4	25	S3 and machining	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/01/03 07:37

S5	51	S3 and (measur\$4 with distance)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/01/03 07:51
S6	2	("20040227044").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2005/01/03 07:51
S7	81	(meinke-p\$).in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/01/03 08:38
S8	14	"3310345"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/01/03 08:38
S9	14	("2818494" "3209460" "3531868" "3944798" "4258474" "4384407" "4477973" "4522555" "4523384" "4703443" "4766674").PN.	US-PGPUB; USPAT; USOCR	OR	ON	2005/01/03 08:39
S10	49	("4891889").URPN.	USPAT	OR	ON	2005/01/03 08:53
S11	40	"measuring robot"	USPAT	OR	ON	2005/01/03 12:48
S12	7193	((73/162,431,866.1,866.5) or (7/167,168) or (409/204,218, 235,264,265,286,337,338,343) or (901/2,10,14,15,16,24,28, 41,44,49,47)).CCLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2005/01/03 12:52
S13	7292	((73/162,431,866.1,866.5) or (7/167,168) or (409/204,218, 235,264,265,286,337,338,343) or (901/2,10,14,15,16,24,28, 41,44,46,47)).CCLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2005/06/30 13:12
S14	2266	S13 and (robot\$4 or parallelogram)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/01/03 12:53
S15	222	S14 and (probe or gauge)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/01/03 12:54
S16	2706079	(DE 3310345-\$).did.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/01/03 12:54
S17	2	(DE-3310345-\$).did.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/01/03 12:54
S18	9076	(machining gauging) and probes	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/03/21 10:06
S19	1097	(machining gauging) and ((measurement measuring) near3 probes)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/03/21 10:21

S20	246	S19 and independ\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/03/21 10:13
S21	2	"20040020311"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/03/21 10:13
S22	2	("6400167").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2005/03/21 10:13
S23	688	robot and (rotary adj (drive mototr))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 10:41
S24	0	S23 and paralleogram	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 10:41
S25	16	S23 and parallelogram	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 10:43
S26	2	("5,180,955").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2005/06/27 10:43
S27	22	"gear teeth" near inspect\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 10:58
S28	324	gear near inspect\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 11:05
S29	6	S28 and robot\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 11:05
S30	1373	gear near measur\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 11:02
S31	26	S30 and robot\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 11:02
S32	1292	gear near5 inspect\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 11:05

S33	19	S32 and robot\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 11:05
S34	1	(ep-396752-\$).did.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 12:04
S35	4	(dalakian-\$).in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 12:04
S36	90167	(noncontact\$3 or (non adj1 contact\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 12:45
S37	6998	(noncontact\$3 or (non adj1 contact\$3)) near3 (measur\$4 inspect\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 12:45
S38	38	S37 and ((measur\$4 inspect\$4) near3 gear\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 12:46
S39	2567	(gear near3 (tooth teeth)) and ((measur\$4 inspect\$4) near3 (tooth teeth gear))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 13:09
S40	104	S39 and robot\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 13:10
S41	2	("4816262").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2005/06/27 13:40
S42	19127	(robot\$4 with (head sensor))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 13:48
S43	1246	S42 and ((head sensor) with slid\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 13:50
S44	3215	((robot robotic) with (head sensor)).ti.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 13:50
S45	95	S44 and ((head sensor) with slid\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2005/06/27 13:50